TITLE OF THE INVENTION

Magnet Apparatus and MRI Apparatus

FIELD OF THE INVENTION

5   The present invention relates to a super conducting magnet which is suitable for a nuclear magnetic resonance imaging (hereinafter, simply called as MRI) device, and, more specifically, relates to a super conducting magnet device which is provided with

10   a broad opening as well as makes easy to access to a measurement object by reducing the outer diameter of the magnet.

BACKGROUND ART

15   Conventionally, it was difficult that a person performing inspection such as a medical doctor accesses a person under inspection during image taking with an MRI device, therefore, the so called Interventional Radiology (hereinafter, simply called

20   as IVR) was as well as difficult.

For example, JP-A-7-106153 (1995) entitled "C Type Super Conducting Magnet" discloses a conventional art for avoiding the above problems.

The above referred to device takes MRI images

25   after inserting a patient between two magnetic poles.

This device is for generating a uniform magnetic field by optimizing the configuration of the magnetic

poles, however, because of weight limitation thereof, a uniform magnetic field space which can be used merely for inspecting a head portion of the patient is generally created.

5   However, in a case of whole-body use MRI device which permits an image taking of such as the abdomen, the chest and the bi-shoulder of a patient representing an inspection object without moving the patient during image taking, it is generally necessary

10   to generate a uniform magnetic field with intensity variation of a few ppm (for example 2~3 ppm) in an image taking region covered by a sphere having a diameter from 40cm to more than 50cm. Accordingly, it is required to develop an MRI device having a magnet

15   which can generates a uniform magnetic field with its intensity variation of a few ppm (for example, 2~3 ppm) in an image taking region covered by a sphere having a diameter from 40cm to more than 50cm while keeping a highly open space feeling in the magnet for

20   an MRI device.

As has been explained above, it was difficult until now to generate a uniform magnetic field over a broad region in a magnet having a broad opening which gives an open space feeling for a person to be

25   inspected (a patient) representing a measurement (image taking) object. Further, there is a problem to have to increase the outer diameter of the magnet in

order to obtain a broad uniform magnetic field space, which causes other problems to deteriorate the open space feeling for the patient and easy access thereto. Still further, when it is intended to enlarge the

5 uniform magnetic field region, which causes a problem of increasing the manufacturing cost of the magnet because the absolute value of magnetomotive forces of coils constituting the magnet has to be increased.

Further, JP-A-3-141619 (1991) discloses a magnet

10 for generating a uniform magnetic field in a broad region in which currents in opposite directions are flown through two coils disposed in outside and inside along a same axis to generate magnetic fields in opposite direction and to superposed the same each

15 other, thereby, a non-uniformity of magnetic field produced by a single coil is canceled out to enlarge a uniform magnetic field region.

Further, JP-A-9-153408 (1997) applied by the present applicants discloses a super conducting magnet

20 device each of a pair of static magnetic field generation sources disposed in vertical direction so as to oppose each other is constituted so as to include one main coil unit for generating static magnetic field and a plurality of coil units for

25 correcting irregular magnetic field, however, JP-A-9-153408 (1997) does not disclose specifically the DC current flow direction in these two sorts of unit

coils.

SUMMARY OF THE INVENTION

An object of the present invention is to provide

5   a super conducting magnet with a broad opening used

for unclear magnetic resonance which generates a

desirable uniform magnetic field in comparison with a

conventional magnet and shows a high open space

feeling through a small outer diameter of the magnet.

10   A first aspect of the magnet device according to

the present invention which achieves the above object

and in which two sets of static magnetic field

generation sources, each being constituted by current

carrying means disposed substantially concentrically

15   with respect to a first direction in order to generate

a uniform magnetic field directing in the first

direction in a finite region, are disposed facing each

other while placing the uniform magnetic field region

therebetween and each of the static magnetic field

20   generation sources is provided with at least four

current carrying means, is characterized in that when

assuming a crossing point of a first axis which is in

parallel with the first direction and passes

substantially the center of the current carrying means

25   and a second axis which crosses the first axis

orthogonally and locates at substantially the equal

distance from the two sets of the static magnetic

field generation sources as a first point and further assuming a first straight line contained on a first plane defined by the first axis, the second axis and the first point and passing through the first point,

5 the current carrying means are disposed in such a manner that, when geometrical centers of cross sections of the current carrying means on the first plane are projected on the first straight line, the current carrying direction of the current carrying

10 means corresponding to the respective projections of each of the static magnetic field generation sources aligns alternatively in positive and negative direction.

A second aspect of the magnet device according to

15 the present invention in which two sets of static magnetic field generation sources, each being constituted by current carrying means and shielding current carrying means for suppressing leakage magnetic field to an external region disposed

20 substantially concentrically with respect to a first direction in order to generate a uniform magnetic field directing in the first direction in a finite region, are disposed facing each other while placing the uniform magnetic field region therebetween and

25 each of the static magnetic field generation sources is provided with at least four current carrying means and at least one shielding current carrying means, is

characterized in that when assuming a crossing point of a first axis which is in parallel with the first direction and passes substantially the center of the current carrying means and a second axis which crosses

5 the first axis orthogonally and locates at substantially the equal distance from the two sets of the static magnetic field generation sources as a first point and further assuming a first straight line contained on a first plane defined by the first axis,

10 the second axis and the first point and passing through the first point, the current carrying means are disposed in such a manner that, when geometrical centers of cross sections of the current carrying means on the first plane are projected on the first

15 straight line, the current carrying direction of the current carrying means corresponding to the respective projections of each of the static magnetic field generation sources aligns alternatively in positive and negative direction.

20   A third aspect of the magnet device according to the present invention in which two sets of static magnetic field generation sources, each being constituted by current carrying means disposed substantially concentrically with respect to a first

25 direction in order to generate a uniform magnetic field directing in the first direction in a finite region, are disposed facing each other while placing

the uniform magnetic field region therebetween and each of the static magnetic field generation sources is provided with a ferromagnetic body functioning as a magnetic pole and at least two current carrying means,

5   is characterized in that when assuming a crossing point of a first axis which is in parallel with the first direction and passes substantially the center of the current carrying means and a second axis which crosses the first axis orthogonally and locates at

10 substantially the equal distance from the two sets of the static magnetic field generation sources as a first point and further assuming a first straight line contained on a first plane defined by the first axis, the second axis and the first point and passing

15 through the first point, the current carrying means are disposed in such a manner that, when geometrical centers of cross sections of the current carrying means on the first plane are projected on the first straight line, the current carrying direction of the

20 current carrying means corresponding to the respective projections of each of the static magnetic field generation sources aligns alternatively in positive and negative direction.

A fourth aspect of the magnet device according to

25 the present invention in which two sets of static magnetic field generation sources, each being constituted by current carrying means and shielding

current carrying means for suppressing leakage magnetic field to an external region disposed substantially concentrically with respect to a first direction in order to generate a uniform magnetic
5 field directing in the first direction in a finite region, are disposed facing each other while placing the uniform magnetic field region therebetween and each of the static magnetic field generation sources is provided with a ferromagnetic body functioning as a
10 magnetic pole, at least two current carrying means and at least one shielding current carrying means, is characterized in that when assuming a crossing point of a first axis which is in parallel with the first direction and passes substantially the center of the
15 current carrying means and a second axis which crosses the first axis orthogonally and locates at substantially the equal distance from the two sets of the static magnetic field generation sources as a first point and further assuming a first straight line
20 contained on a first plane defined by the first axis, the second axis and the first point and passing through the first point, the current carrying means are disposed in such a manner that, when geometrical centers of cross sections of the current carrying
25 means on the first plane are projected on the first straight line, the current carrying direction of the current carrying means corresponding to the respective

projections of each of the static magnetic field generation sources aligns alternatively in positive and negative direction.

A fifth aspect of the magnet device according to the present invention in which two sets of static magnetic field generation sources, each being constituted by current carrying means disposed substantially concentrically with respect to a first direction in order to generate a uniform magnetic field directing in the first direction in a finite region, are disposed facing each other while placing the uniform magnetic field region therebetween and each of the static magnetic field generation sources is provided with three current carrying means, is characterized in that when assuming a crossing point of a first axis which is in parallel with the first direction and passes substantially the center of the current carrying means and a second axis which crosses the first axis orthogonally and locates at substantially the equal distance from the two sets of the static magnetic field generation sources as a first point and further assuming a first straight line contained on a first plane defined by the first axis, the second axis and the first point and passing through the first point, the current carrying means are disposed in such a manner that, when geometrical centers of cross sections of the current carrying

means on the first plane are projected on the first straight line, the current carrying direction of the current carrying means corresponding to the respective projections of each of the static magnetic field

5 generation sources aligns alternatively in positive and negative direction.

A sixth aspect of the magnet device according to the present invention in which two sets of static magnetic field generation sources, each being

10 constituted by current carrying means and shielding current carrying means for suppressing leakage magnetic field to an external region disposed substantially concentrically with respect to a first direction in order to generate a uniform magnetic

15 field directing in the first direction in a finite region, are disposed facing each other while placing the uniform magnetic field region therebetween and each of the static magnetic field generation sources is provided with three current carrying means and at

20 least one shielding current carrying means, is characterized in that when assuming a crossing point of a first axis which is in parallel with the first direction and passes substantially the center of the current carrying means and a second axis which crosses

25 the first axis orthogonally and locates at substantially the equal distance from the two sets of the static magnetic field generation sources as a

first point and further assuming a first straight line contained on a first plane defined by the first axis, the second axis and the first point and passing through the first point, the current carrying means

5 are disposed in such a manner that, when geometrical centers of cross sections of the current carrying means on the first plane are projected on the first straight line, the current carrying direction of the current carrying means corresponding to the respective

10 projections of each of the static magnetic field generation sources aligns alternatively in positive and negative direction.

Now, magnetic field in a magnet used in an MRI device will be explained thereinbelow.

15 When assuming that the center axis of the magnet device is z axis, r and θ represent a coordinate position in a polar coordinate assuming the center of the magnet device as origin and $P_n(\cos \theta)$ is Legendre's function of nth degree, magnetic field Bz

20 in z direction near the center portion of the magnet device can generally be developed and expressed in the following equation (1);

$$Bz = \sum_{n=0}^{\infty} d_n r^n p_n(\cos \theta) \qquad \cdots (1)$$

wherein d_0 is a uniform magnetic field and d_1, d_2, d_3,

25 d_4, d_5, $d_6 \cdots$ are irregular magnetic field intensities

which deteriorate uniformity of the magnetic field. When the magnet is arranged symmetric with respect to the center plane thereof, d_1, d_3, d_5··· among the above irregular magnetic field components become zero

5   because of the symmetry nature. Accordingly, only the irregular magnetic field components d_2, d_4, d_6··· are required to take into account as the irregular magnetic fields which deteriorate uniformity of the magnetic field.

10   An MRI use magnet is required to form a uniform magnetic field having a few ppm order variation in an image taking region near the magnet center portion. A uniform magnetic field generation is achieved by successively eliminating the irregular magnetic field

15   components d_2, d_4, d_6··· from lower degree terms among developed terms according to equation (1) expressing a magnetic field in z direction near the center portion of the magnet. Form equation (1) it will be understood that if the irregular magnetic field

20   components are eliminated up to high degree terms, a space of uniform magnetic field will be expanded.

A magnet device for an MRI device used such as in hospitals is required to generate a uniform magnetic field within ±5ppm variation rate in a spherical

25   region having a diameter of 40cm~50cm.

In order to fulfill the above requirement, proper magnet designs are usually employed so that the

irregular magnetic field components from the second degree to 8th degree or 10th degree in that d_2, d_4, d_6, d_8 and d_{10} become zero.

As has been explained above, in order to generate a uniform static magnetic field, at first it is necessary to make zero the second degree irregular magnetic field component d_2.

For the sake of simplicity, a magnetic field formed by an annular ring line current is discussed. Among developed terms expressed by the equation (1) of the magnetic field produced by the annular ring line current as shown in Fig. 13, plots of d_2 depending on $\beta = a/b$ are shown in Fig. 14. Wherein, a represents a radius of the annular ring line current, b represents a distance of the annular ring line current from the origin in z axis direction and i represents a current value, and in the plots it is assumed that b=1 and i=1. As will be apparent from Fig. 14, the developed term coefficient d_2 becomes zero when $\beta = 2$, in other words, the second degree irregular magnetic field component becomes zero with the arrangement which is already known as a Helmholtz coil.

In an MRI device use magnet, it is necessary to eliminate at first the secondary degree irregular magnetic field component as has been explained above, however, as will be understood from Fig. 14, if coils

14

through which currents in the same direction flow are only used, it is impossible to reduce the coil diameter than that of the Helmholz coil arrangement.

Accordingly, two annular ring currents each having β smaller than 2 as shown in Fig. 15 are discussed. Wherein, it is assumed that a radius and current value of an annular ring current 175 are respectively a_1 and $i=1$, and a radius and current value of an annular ring current 176 are respectively a_2 and $i=-0.4$. Values of d_2 produced respectively by the two coils depending on β are plotted in Fig. 16. Curves 177 and 178 respectively correspond to the annular ring currents 175 and 176. As will be apparent from Fig. 16, if the values β_1 and β_2 are properly selected, it is possible to make the absolute values of respective d_2 terms produced by the annular ring currents 175 and 176 equal, but the signs thereof to be opposite each other, thereby, the sum of irregular magnetic field components d_2 produced by the two annular ring currents 175 and 176 can be rendered zero. Namely, through an arrangement of a plurality of coils each having different polarity in alternative manner in radial direction the secondary degree irregular magnetic field component can be eliminated with coils having a smaller outer diameter than that of a Helmholz coil.

Now, an exemplary arrangement in which the secondary and quadratic degree irregular magnetic field components are eliminated will be explained. Fig. 21 shows an optimum designed coil arrangement

5 which is determined through computer programs so as to minimized the sum of absolute values of magnetomotive force according to the present invention. As is illustrated in Fig. 21, in order to eliminate irregular magnetic field components up to the

10 quadratic degree and to reduce the outer diameter of the coils than the arrangement of a Helmholz coil, total of six pieces of coils is necessary, in that three for one of two static magnetic field generation sources and other three for the other static magnetic

15 field generation source. Coils of which current flow direction are positive and negative are alternatively arranged in the radial direction. The absolute values of magnetomotive force are increased according to the radial diameter size thereof.

20 How the secondary and quadratic degree irregular magnetic field components are eliminated in this coil arrangement will be explained with reference to Figs. 22 and 23.

Fig. 22 shows secondary degree irregular magnetic

25 field components produced by the respective coils shown in Fig. 21, and Fig. 23 shows quadratic degree irregular magnetic field components produced by the

respective coils as shown in Fig. 21. Curves 211, 212 and 213 are sensitivity curves relating to secondary degree irregular magnetic field components corresponding to magnetomotive forces produced by

5   coils #1, #2 and #3 in Fig. 21 with respect to β. Curves 214, 215 and 216 are sensitivity curves of the quadratic degree irregular magnetic field components corresponding to the magnetomotive forces of the coils #1, #2 and #3 as shown in Fig. 21 with respect to β.

10 The values β of geometric centers of the cross sections of the coils #1, #2 and #3 are respectively 0.30, 0.80 and 1.46. Accordingly, the secondary degree irregular magnetic field component produced by, for example, coil #3 assumes the value indicated by

15 the numeral 203. Accordingly, with the coil arrangement of Fig. 21 the coils #1, #2 and #3 respectively produce the secondary degree irregular magnetic field components as indicated by numerals 201, 202 and 203 in Fig. 22, and the positions and

20 magnetomotive forces of the respective coils are set so that the sum of these secondary degree irregular magnetic field components is rendered zero. Likely, the coils #1, #2 and #3 respectively produce the quadratic degree irregular magnetic field components

25 as indicated by numerals 204, 205 and 206 in Fig. 23, and the positions and magnetomotive forces of the respective coils are set so that the sum of these

quadratic degree irregular magnetic field components is rendered zero.

These relationships can be qualitatively explained as follows. As has been explained above, at first it is necessary to eliminate the secondary degree irregular magnetic field components, for this reason, the positions of coils #2 and #3 are mostly determined on this base. Although the coil #3 produces the quadratic degree irregular magnetic field component as indicated by the numeral 206 to be eliminated, however, as seen from the sensitivity curves in Figs. 22 and 23, it will be understood that no solution which renders both the secondary and quadratic degree irregular magnetic field components zero can not exist, only when the positions and the magnetomotive forces of the coils #2 and #3 are varied. Accordingly, the coil #1 is newly added of which radius is the smallest and of which magnetomotive force is directed positive to produce the quadratic degree irregular magnetic field component indicated by the numeral 204, thereby, the total sum of quadratic degree irregular magnetic field components is reduced zero. Further, in order to minimize the sum of absolute values of magnetomotive forces, the positions of the respective coils are determined in such a manner that the positions corresponding near to the peaks of the respective

sensitivity curves are avoided and the positions showing as much as small sensitivity are selected. Actually, since the coil #1 produces the secondary degree irregular magnetic field component as indicated by the numeral 201, it is necessary to adjust to render the secondary degree irregular magnetic field components zero as a whole as well as the quadratic degree irregular magnetic field components zero, accordingly an optimum arrangement of the coils is correctly determined through computer programs incorporating the sensitivity curves. In order to eliminate the secondary and quadratic degree irregular magnetic field components with group of coils each having a smaller radius than that of a Helmholz coil, it is necessary to arrange coils with positive and negative current flow directions alternatively as has been explained above, this is because the sensitivity curves of irregular magnetic field components of respective degrees show the shapes as illustrated in Fig. 19. The respective sensitivity curves are physically and inherently determined based on an electro-magnetic phenomenon. The present invention is brought about on the analysis of the sensitivity curves, accordingly, the result of the present invention which is obtained by making use of the analysis is non-ambiguously determined.

Although in the present embodiment a specific

explanation on elimination of the irregular magnetic field components of higher degree equal to and more than 6 degree is omitted, the same principle can be applied thereto, in that through the alternate

5 arrangement of coils having different polarity in the radial direction thereof, a magnet of which irregular magnetic field components are eliminated up to high degrees and which generates an extremely uniform magnetic field can be constituted with a magnet having

10 a smaller outer diameter than that of a Helmholz coil. Further, the present structure provides a minimum number of coils which eliminates the irregular magnetic field components up to necessary degree, accordingly, the sum of the absolute values of

15 magnetomotive forces of the respective coils shows minimum among any conceivable coil arrangement.

The above coil arrangement can be determined through computer programs making use of the sensitivity curves of the irregular magnetic field

20 intensities of respective degrees as shown in Fig. 19. Since it is difficult to explain the function thereof, the nature of the solution is qualitatively explained. Fig. 20 shows a general space distribution of sixth degree irregular magnetic field intensity. In the

25 drawing, the origin represents the center of the magnet, z axis corresponds to the center axis of the magnet, ρ axis represents an axis in radial direction

which passes through the center of the magnet and is directed to an arbitrary direction, and the abscissa represents sixth degree irregular magnetic field intensity. As will be understood from the equation

5 (1) referred to previously, the intensity at the origin is zero and the intensity increases in proportion to 6th power of the distance according to the distance increase from the origin. However, depending on the nature of $P_n(\cos \theta)$ the intensity is

10 expressed by a space distribution having positive and negative values with respect to azimuth angle θ. Accordingly, for example, with regard to the space distribution of 6th degree irregular magnetic field component through alternative arrangement of coils

15 having positive and negative polarity, the 6th degree irregular magnetic field component can be effectively canceled out. The alternative arrangement of coils having positive and negative polarity can be generalized in such a manner that when geometric

20 centers of cross sections of respective coils are projected on a straight line passing through the origin, current polarity of the coils corresponding to the projected centers is aligned alternatively in positive and negative on the straight line as will be

25 defined in claims.

Now, advantages of the present invention will be specifically explained by making use of numerical

calculation result. Fig. 17 shows a calculation result based on the principle of the present invention and at the same time illustrates a coil arrangement and contours representing magnetic field uniformity.

5 The respective contours of magnetic field uniformity indicate ±1, ±5 and ±10ppm from the inside. Wherein, the current density in the coils is 100A/mm², the interval between the upper and lower coils is 1.0m and the outer diameter of the coils is limited to 1.7m.

10 Further, the intensity of the center magnetic field is 0.4T and the second through 6th degree irregular magnetic field components are rendered zero near the center portion.

As will be apparent from Fig. 17, when the

15 geometric centers of the respective coil cross sections on z-ρ plane in the first quadrant are projected on the ρ axis, the current flow directions at the projected centers corresponding to the respective coils are aligned alternatively in positive

20 and negative. With the arrangement method according to the present invention the sum of absolute values of magnetomotive force by the respective coils is minimized, namely, the present method is understood the most reasonable one.

25   Fig. 18 shows one of calculation results not based on the principle of the present invention.

The current density in the coils, the intensity

of the center magnetic field, and the degrees of canceled out irregular magnetic field components are substantially the same as these of Fig. 17. In the calculation example in Fig. 18, when the geometrical

5   centers of the respective coil cross sections on z-ρ plane are projected on any straight lines on the z-ρ plane passing the origin, their current flow directions at the projected centers corresponding to the respective coils are never aligned alternatively

10 in positive and negative, namely, Fig. 18 arrangement never follows the principle of the present invention. When comparing the calculation example of Fig. 18 with the calculation example of Fig. 17, their space distributions of generated magnetic field are

15 substantially the same, however, in Fig. 18 calculation example requires 1.4 times of the sum of absolute values of magnetomotive force produced by the coils for achieving the same space magnetic field distribution and further requires two more coils in

20 total. Namely, the most advantageous effect of the present invention is to provide a coil arrangement which shows the minimum sum of absolute value of magnetomotive force among possible coil arrangements which produce a magnetic field distribution having a

25 predetermined space distribution. In the coil arrangement as shown in Fig. 18 which does not follow the principle of the present invention, since the sum

of absolute values of magnetomotive force of the coils is 1.4 times larger when compared with the coil arrangement as shown in Fig. 17 which follows the principle of the present invention and the number of

5 coils also increases by 2, a variety of demerits are caused such as an increase of electro-magnetic force between coils, complexing of support structure and weight increase thereby and weight increase of cooling means, and as a result, production cost of the magnet

10 extremely increases, therefore, it is understood that the conventional design method as exemplified in Fig. 18 is very inefficient one. Further, in the calculation result as shown in Fig. 17 which is based on the principle of the present invention, the

15 absolute value of magnetomotive force of a coil having the largest average radius is larger than the absolute values of magnetomotive force of other coils and it is further understood that when the respective coils in the first quadrant is projected on ρ axis, the

20 absolute values of magnetomotive force of the respective coils are aligned according to the magnitudes thereof. These setting methods of the magnetomotive forces are also conditions which minimizes the sum of absolute values of magnetomotive

25 force of the entire coils.

Further, a magnet device for an open type MRI device as disclosed in U.S. Patent No.5,410,287 is

directed to a horizontal magnetic field type, however, the coil arrangement therein is somewhat similar to that explained in connection with Fig. 18.

Further, for a whole-body MRI it is necessary to generate a uniform static magnetic field having variation within ±5 ppm in a spherical region having a diameter of 40cm~50cm. For this requirement it is necessary to make zero at least up to 8th degree irregular magnetic field components, and for the purpose of design freedom at least four coils are necessary for each magnet assembly. In a coil design which eliminates irregular magnetic field components up to 6th degree, 8th degree irregular magnetic field component dominantly controls the magnetic field uniformity, therefore, it is necessary to reduce the intensity of the 8th irregular magnetic field as much possible, and for this necessary it is preferable to limit the magnetomotive force produced by the respective coils. Although not illustrated as calculation examples here, similar calculation as in Fig. 17 and Fig. 18 examples can be performed for the case of three coils, and it is confirmed that if the three coils are arranged in the radial direction so that the current flow directions therein align alternatively in positive and negative, the sum of absolute values of the coil magnetomotive force is minimized.

Because of size limitation of such as a cryostat and a low temperature vessel, necessary number of coils can not sometimes be disposed in the radial direction, in such instance, it is sufficient if a coil is disposed along the inner wall of the low temperature vessel. The present invention discloses such generalized coil arrangement methods, and the specific examples thereof will be explained as embodiments hereinbelow.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a perspective view of an open type MRI device using a super conducting magnet according to the present invention;

Fig. 2 is a cross sectional view of a super conducting magnet representing an embodiment according to the present invention;

Fig. 3 is a cross sectional view of a super conducting magnet representing another embodiment according to the present invention;

Fig. 4 is a cross sectional view of a super conducting magnet representing still another embodiment according to the present invention;

Fig. 5 is a cross sectional view of a super conducting magnet representing a further embodiment according to the present invention;

Fig. 6 is a cross sectional view of a super

conducting magnet representing a still further embodiment according to the present invention;

Fig. 7 is a cross sectional view of a super conducting magnet representing a still further embodiment according to the present invention;

Fig. 8 is a cross sectional view of a super conducting magnet representing a still further embodiment according to the present invention;

Fig. 9 is a cross sectional view of a super conducting magnet representing a still further embodiment according to the present invention;

Fig. 10 is a cross sectional view of a super conducting magnet representing a still further embodiment according to the present invention;

Fig. 11 is a cross sectional view of a super conducting magnet representing a still further embodiment according to the present invention;

Fig. 12 is a cross sectional view of a super conducting magnet representing a still further embodiment according to the present invention;

Fig. 13 is a view for explaining an annular ring current;

Fig. 14 is a diagram showing a sensitivity curve of secondary degree irregular magnetic field intensity produced by the annular ring current as shown in Fig. 13;

Fig. 15 is a view for explaining two annular ring

currents;

Fig. 16 is a diagram showing sensitivity curves of second degree irregular magnetic field intensity produced by the two annular ring currents as shown in Fig. 15;

Fig. 17 is a diagram showing a numerical calculation example of a coil arrangement according to the present invention and contours of the magnetic field uniformity produced thereby;

Fig. 18 is a diagram showing a numerical calculation example of a coil arrangement according to the present invention and contours of the magnetic field uniformity produced thereby;

Fig. 19 is a diagram showing sensitivity curves of irregular magnetic field intensities from second degree to 6th degree produced by the annular ring current as shown in Fig. 13;

Fig. 20 is three dimensional plots showing a space distribution of 6th degree irregular magnetic field component;

Fig. 21 shows an optimum designed coil arrangement through computer programs so that the sum of absolute values of magnetomotive force is minimized according to the principle of the present invention;

Fig. 22 shows second degree irregular magnetic field components produced by the respective coils as shown in Fig. 21; and

Fig. 23 shows 4th degree irregular magnetic field components produced by the respective coils as shown in Fig. 21.

5   BEST MODES FOR CARRYING OUT THE PRESENT INVENTION

Hereinbelow, embodiments of the present invention will be explained specifically with reference to Fig. 1 through Fig. 12.

Fig. 1 is a perspective view of an open type
10 super conducting MRI device using a super conducting magnet representing an embodiment according to the present invention. Fig. 2 is a cross sectional view on z-x plane of the super conducting magnet 1 among many constituting elements of the open type MRI device
15 in Fig. 1.

The MRI device as shown in Fig. 1 produces a uniform magnetic field in z axis direction in an open region 2 by upper and lower super conduction magnet assemblies 6 and 7, and permits MRI image taking at
20 the center portion of the open region 2. A patient 4 is carried by a bed and movable table 3 so that an image taking portion of the patient 4 positions at the center portion of the open region 2. The upper and lower super conducting magnetic assemblies 6 and 7 are
25 magnetically coupled by column shaped external ferromagnetic bodies 10 and are further designed so as to suppress leakage magnetic field. With thus

structured MRI, claustrophobia to which the patient 4 tends to be subjected during image taking is extremely reduced and the patient 4 can even be given an open space feeling, thereby, a psychological pressure of the patient 4 with respect to the image taking is greatly reduced.   Further, an access of a medical doctor or an inspection engineer 5 to the patient 4 during the image taking can be facilitated significantly.   In particular, an access of the medical doctor or the inspection engineer 5 to an object portion of the patient 4 during the image taking is permitted, therefore, an Interventional Radiology (IVR) is enabled which broadens possibility of medical treatment.

Further, as an advantage of the MRI device having the structure as shown in Fig. 1, since the direction of static magnetic field is orthogonal with respect to the longitudinal direction of a human body, a solenoid coil can be used for a probe for receiving NMR signals.   The sensitivity of such solenoid type probe is theoretically 1.4 times higher than that of a saddle shaped or bird cage shaped probe used for the horizontal magnetic field type MRI device.

Accordingly, when assuming that the center magnetic field intensity is equal each other, the vertical magnetic field type MRI having the structure as shown in Fig. 1 can take a further accurate

tomographic images with a further higher speed in comparison with the conventional horizontal magnetic field type MRI device.

As has been mentioned above, the MRI device structured according to the concept as shown in Fig. 1 has a variety of advantages, however, a key for achieving a highly open space feeling from structural point of view is how to reduce the diameter of the upper and lower magnetic assemblies 6 and 7. The present invention exactly relates to the key and provides a magnet assembly structure of which outer diameter is small and of which production cost is inexpensive, and moreover which generates a desired uniform magnetic field.

Now, the structure of the magnet assemblies 6 and 7 will be explained with reference to Fig. 2. The upper and lower magnet assemblies 6 and 7 are surrounded at the outer circumferences thereof by respective ferromagnetic bodies so as to suppress leakage magnetic field. More specifically, disk shaped external ferromagnetic bodies 8 and 8' and cylindrical external ferromagnetic bodies 9 and 9' surround around upper and lower vacuum vessels 11 and 11', and the upper and lower ferromagnetic bodies 8, 8' and 9, 9' are magnetically coupled by the column shaped external ferromagnetic bodies 10. As the external ferromagnetic bodies used in the present

embodiment, any material will do, if such shows ferromagnetic property so that a variety of material can be used, however, in view of magnetic properties, cost and mechanical strength ion is generally

5   preferable. Further, when a weight lightening of the ferromagnetic bodies is required, a material having a high permeability can be used. Through the surrounding of the circumferences with the external ferromagnetic bodies magnetic passages are formed for

10   magnetic fluxes possibly leaking outside from the device to thereby suppress the leakage magnetic field from expanding far.

Main super conducting coils 13, 13', 14, 14', 15, 15' and 16, 16' are disposed substantially symmetric

15   in upper and lower positions while sandwiching a uniform magnetic field region at the center of the magnet and substantially concentrically with respect to z axis, and produces a uniform magnetic field in vertical direction, namely in z axis direction. The

20   upper and lower super conducting coils are disposed inside respective cooling containers 12 and 12', and the upper and lower cooling containers 12 and 12' are accommodated in respective vacuum vessels 11 and 11'. Further, for the sake of simplicity although the

25   illustration in Fig. 2 is omitted, there is a structure for supporting the super conducting coils and further there is provided a heat shielding member

between the vacuum vessels and the cooling containers for preventing penetration of radiation heat. Liquid helium is stored inside the cooling vessels and cools the super conducting coils to a super low temperature

5 of 4.2°K.

The upper and lower vacuum vessels are held by coupling tubes 17 disposed therebetween while keeping a predetermined distance. These coupling tubes 17 work to support mechanically the upper and lower

10 vacuum vessels 11 and 11', however, can include a function of thermally connecting the upper and lower cooling containers. If such function is added, it becomes unnecessary to provide each one cryostat for upper and lower cooling containers, thereby, the

15 system can be operated with a single cryostat. Further, the number of the coupling tubes 17 and the column shaped ferromagnetic bodies 10 needs not to be limited to two as illustrated, but can be increased three, four and more. Further, in order to obtain a

20 further open space feeling a single support column forming an overhang structure can be used.

In the present embodiment, the respective four main super conducting coils 13, 13', 14, 14', 15, 15' and 16, 16' inside the respective upper and lower

25 magnet assemblies are arranged so as to align their polarities alternatively in positive and negative. More precisely, when assuming a certain straight line

18 passing through the center of the magnet assemblies on any plane containing z axis representing the center axis of the magnet (herein, for the sake of explanation simplicity z-x plane is assumed) and when

5   the geometric center of the cross sections of the respective super conducting coils in the first quadrant on the z-x plane are projected on the straight line 18, the polarities of current flow of the projections on the straight line 18 corresponding

10 to the respective coils align alternatively in positive and negative. In other words, in the coil 16 a current is flown to the direction causing the main magnetic field and of which direction is assumed as the positive direction, a current in the negative

15 direction is flown in the coils 13 and 15, and a current in positive direction is flown in the coil 14.

Further, as seen from the drawing, the magnitude of absolute values of magnetomotive force of the respective coils 16, 15, 14 and 13 is larger in this

20 appearing order and it is understood that when the respective coils in the first quadrant on the z-x plane are projected on the straight line 18, the absolute values of magnetomotive force of the respective coils align in their order of magnitude.

25 Further, the absolute value of magnetomotive force of the coil 16 having the maximum average radius is the largest. These magnetomotive force setting method is

also one of the conditions which minimizes the sum of absolute values of magnetomotive force of the entire coils.

The positions and magnetomotive forces of the
5 respective coils are designed based on calculations so as to form a uniform magnetic field distribution. Although arrangement of coils which produces a uniform magnetic field is infinite, however, the above arrangement method as has been explained in the
10 Summary of the Invention gives the minimum sum of absolute values of magnetomotive force, thereby, the magnet can be produced with minimum cost. Further, since the sum of absolute values of magnetomotive force is small, the cross sectional areas of the
15 respective coils are reduced, thereby, the diameters of the magnet assemblies can also be reduced. Still further, the present embodiment is designed to render the irregular magnetic field components from second degree to 8th degree zero, and for this purpose four
20 coils are disposed in respective magnet assemblies. As a result, a uniform magnetic field of 45cm dsv (diameter of spherical volume) with ±4 ppm variation is obtained at the center of the magnet which sufficiently fulfills the specification for a whole-
25 body MRI.

Hereinbelow, other embodiments according to the present invention will be explained with reference to

the drawings.

Fig. 3 is a cross sectional view of a super conducting magnet for an open type MRI representing another embodiment according to the present invention. The constitutional structure of the present embodiment is substantially the same as the super conducting magnet as shown in Figs. 1 and 2 except for a provision of super conducting shielding coils 29 and 29' for reducing the weight of the external ferromagnetic bodies suppressing leakage magnetic field. According to general naming of leakage magnetic field shielding methods, the method of Fig. 2 embodiment is called as a passive shielding method and the method of Fig. 3 embodiment is called as a hybrid shielding method. When the geometric centers of the cross sections of main super conducting coils 25, 25', 26, 26', 27, 27' and 28, 28' except for the super conducting shielding coils 29 and 29' in Fig. 3 on the z-x plane in the first quadrant are projected on a straight line 30 (an imaginary line), the coils are arranged in such a manner that the current flow direction of the corresponding coils to the projections aligns alternatively in positive and negative on the straight line 30.

Fig. 4 is a cross sectional view of a super conducting magnet for an open type MRI device representing still another embodiment according to the

present invention. The present embodiment shows an active shielding type super conducting magnet. The present embodiment suppresses leakage magnetic field only by the shielding coils and eliminates

5 ferromagnetic shielding bodies such as iron, therefore, the weight thereof is minimized. When the geometric centers of the cross sections of main super conducting coils 34, 34', 35, 35', 36, 36' and 37, 37' except for the super conducting shielding coils 39 and

10 39' in Fig. 4 on the z-x plane in the first quadrant are projected on a straight line 40, the coils are arranged in such a manner that the current flow direction of the corresponding coils to the projections aligns alternatively in positive and

15 negative on the straight line 40.

In the above embodiment, the magnet assemblies are constituted basically to produce a uniform magnetic field by air-core coils and to suppress leakage magnetic field by the external ferromagnetic

20 bodies or the shielding coils. Hereinbelow, embodiments according to the present invention which positively makes use of ferromagnetic bodies functioning as magnetic poles for producing the uniform magnetic field are disclosed. Figs. 5 through

25 12 are cross sectional views of super conducting magnets for an open type MRI representing further embodiments according to the present invention.

The magnet as shown in Fig. 5 is designed in such a manner that magnetic pole shaped ferromagnetic bodies 44 and 44' disposed inside disk shaped external ferromagnetic bodies 41 and 41' function to enhance

5   the center magnetic field intensity and to reduce the share to be borne by the super conducting coils for the center magnetic field intensity as well as to reduce the sum of absolute values of magnetomotive force of the super conducting coils.   Since the

10   uniformity of magnetic field is primarily achieved by the arrangement of the super conducting coils and the division manner of their magnetomotive forces, the present arrangement is based on the principle of the present invention.   Namely, where the geometric

15   centers of the cross sections of main super conducting coils 48, 48', 49, 49', 50, 50' and 51, 51' in Fig. 5 on the z-x plane in the first quadrant are projected on a straight line 52, the coils are arranged in such a manner that the current flow direction of the

20   corresponding coils to the projections aligns alternatively in positive and negative on the straight line 52.

In the magnet as shown in Fig. 6, the magnetic poles are further enlarged in comparison with the

25   magnet as shown in Fig. 5 and the burden with regard to magnetomotive forces of super conducting coils is further reduced.   The present embodiment is

constituted to optimize the shape of the magnetic poles and to produce a certain level of uniform magnetic field only with the magnetic poles. Accordingly, a small number of super conducting coils

5 will do and in the present embodiment each two super conducting coils in respective upper and lower magnet assemblies can produce sufficient uniform magnetic field. As has been explained in the Summary of the Invention, the current flow direction of the two super

10 conducting coils 60, 60' and 61, 61' are opposite each other, thereby, the second degree irregular magnetic field components are eliminated with the small magnet assemblies. Namely, a current is flown in the outside super conducting coils in the direction producing the

15 main magnetic field. On the other hand, a current in the opposite direction is flown in the inside super conducting coils.

In the magnet as shown in Fig. 7, a rough uniform magnetic field is produced by the magnetic poles

20 having an optimized configuration and three super conducting coils are disposed in the respective magnet assemblies so as to further enhance the uniformity of the magnetic field. The main super conducting coils 70, 70', 71, 71' and 72, 72' are arranged so as to

25 produce a uniform magnetic field with a limited radius and with a minimum magnetomotive force in such a manner that the current flow direction of the

corresponding coils to the projections aligns
alternatively in positive and negative on the straight
line 73 as shown in Fig. 7 according to the principle
of the present invention.

5   A magnet as shown in Fig. 8 is substantially the
same as the magnet as shown in Fig. 7 except for the
provision of super conducting shielding coils 84 and
84' for reducing the weight of the external
ferromagnetic bodies for suppressing leakage magnetic
10 field. In the present embodiment, the main super
conducting coils 81, 81', 82, 82' and 83, 83' except
for the shielding coils 84 and 84' are arranged so as
to produce a uniform magnetic field with a limited
radius and with a minimum magnetomotive force in such
15 a manner that the current flow direction of the
corresponding coils to the projections aligns
alternatively in positive and negative on the straight
line 85 as shown in Fig. 8 according to the principle
of the present invention.

20   Figs. 9 and 10 are other embodiments of super
conducting magnets for an open type MRI which produce
a uniform magnetic field through combinations of
magnetic poles and super conducting coils. The both
magnets are principally constituted based on the
25 following concept that the magnetic poles functions to
strengthen the center magnetic field intensity so as
to save magnetomotive forces of the coils and the

uniformity of the magnetic field is achieved by the arrangement of the coils. Although the configuration of magnetic pole shaped ferromagnetic bodies 89, 89' and, 101, 101' is optimized, since the bodies are

5 located away from the center portion of the magnet serving as the image taking region, it is impossible to produce the uniform magnetic field only with modification of the magnetic pole configuration. Therefore, in Figs. 9 and 10 embodiments, with four

10 and three super conducting coils for each assembly a uniform magnetic field is produced. Further, in Fig. 10 embodiment, the outer circumferential portions of vacuum vessels 102 and low temperature containers 103 are expanded so as to receive the end portion coils

15 107 having a larger magnetomotive forces. Further, with such configuration, the magnetic pole shaped ferromagnetic bodies 101 and 101' can be located near to the image taking region, thereby the share borne by the magnetic poles for strengthening the center

20 magnetic field intensity can be increased, thus the magnetomotive force to be borne by the super conducting coils is saved. The main super conducting coils in both embodiments are arranged so as to produce a uniform magnetic field with a limited radius

25 and with a minimum magnetomotive force in such a manner that the current flow direction of the corresponding coils to the projections aligns

alternatively in positive and negative on the straight line 97 or x axis 108 as shown in Fig. 9 or 10 according to the principle of the present invention.

Figs. 11 and 12 show further embodiments in which
5　ferromagnetic body elements are disposed inside the low temperature containers primarily for reducing the magnetomotive forces to be induced by the coils. With regard to leakage magnetic field suppressing method, Fig. 11 embodiment uses a passive shielding method and
10　Fig. 12 embodiment uses an active shielding method. Inner ferromagnetic bodies 119, 119', 120, 120' and 131, 131', 132, 132' are formed in an annular ring shape and are disposed respectively between super conducting coils. When disposing these ferromagnetic
15　body elements in such position, the magnetomotive forces to be induced by the coils can be effectively reduced. Likely, in the present embodiments, the super conducting coils constituting the main coils are arranged so as to produce a uniform magnetic field
20　with a limited radius and with a minimum magnetomotive force in such a manner that the current flow direction of the corresponding coils to the projections aligns alternatively in positive and negative on the straight line 122 or 133 as shown in Fig. 11 or 12 according to
25　the principle of the present invention.

Hitherto, the present invention has been explained with reference to the concrete embodiments.

In the above embodiments, all of the coils were super conducting coils, however, the coils according to the present invention are not limited to the super conducting coils. For example, coils using copper

5   wires can be used, further, any materials which carry current can be acceptable. For the present invention a variety of embodiments can be conceived a part of which has been explained above, therefore, the present invention should never be limited to the specific

10 embodiments disclosed.

As has been explained hitherto, according to the present invention, a super conducting magnet, device for an open type MRI which is provided with a broad opening and is obtainable a broad uniform magnetic

15 field production region with a high magnetic field intensity and with less leakage magnetic field and being stable in time, is further improved which provides a further higher open space feeling and permits a desirable access to a patient representing

20 an inspection object through reducing the diameter of the magnet which also permits manufacturing cost reduction.

Further, according to the present invention, an MRI device can be realized which provides a higher

25 open feeling and permits a desirable access to an inspection object.

INDUSTRIAL FEASIBILITY

As has been explained above, the magnet device according to the present invention is useful for a magnet device for a medical treatment use MRI device, in particular applicable for a super conducting magnet device for an open and vertical magnetic field type MRI device.